Quadratic hedging schemes for non-Gaussian GARCH models

Alexandru Badescu\textsuperscript{1}, Robert J. Elliott\textsuperscript{2,3}, and Juan-Pablo Ortega\textsuperscript{4}

Abstract

We propose different schemes for option hedging when asset returns are modeled using a general class of GARCH models. More specifically, we implement local risk minimization and a minimum variance hedge approximation based on an extended Girsanov principle that generalizes Duan’s (1995) delta hedge. Since the minimal martingale measure fails to produce a probability measure in this setting, we construct local risk minimization hedging strategies with respect to a pricing kernel. These approaches are investigated in the context of non-Gaussian driven models. Furthermore, we analyze these methods for non-Gaussian GARCH diffusion limit processes and link them to the corresponding discrete time counterparts. A detailed numerical analysis based on S&P 500 European Call options is provided to assess the empirical performance of the proposed schemes. We also test the sensitivity of the hedging strategies with respect to the risk neutral measure used by recomputing some of our results with an exponential affine pricing kernel.

Keywords: GARCH models, local risk minimization, martingale measure, bivariate diffusion limit, minimum variance hedge.

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\textsuperscript{1}Department of Mathematics and Statistics, University of Calgary, Calgary, Canada.
\textsuperscript{2}Corresponding author: School of Mathematical Sciences, University of Adelaide, SA 5005, Australia, Phone: +61 8 8313 5077, Fax: +61 8 8313 3696. E-mail: relliott@ucalgary.ca
\textsuperscript{3}Department of Mathematics and Statistics, University of Calgary, Calgary, Canada.
\textsuperscript{4}Centre National de la Recherche Scientifique, Département de Mathématiques de Besançon, Université de Franche-Comté, UFR des Sciences et Techniques, 16, route de Gray, F-25030 Besançon cedex, France.
1 Introduction

Many empirical studies have shown strong evidence against some of the underlying assumptions of the Black-Scholes (1973) model, in particular the constant value that is assumed for the volatility. The incorporation of stochastic volatility in modeling the dynamics of asset returns plays a major role in explaining some of the stylized properties of financial time series. In particular, the pricing and hedging of options based on stochastic volatility (SV) models have been extensively studied in both discrete and continuous-time. The discrete-time literature has been dominated by the Generalized Autoregressive Conditionally Heteroskedastic (GARCH) models introduced by Engle (1982) and Bollerslev (1986). Although these models have been investigated for pricing, they have rarely been used for option hedging.\footnote{A very recent survey of the major contributions to GARCH option pricing has been provided by Christoffersen et al. (2013).}

The first proposal in this direction can be found in Duan (1995) who introduced a delta hedge obtained as the partial derivative of the option price with respect to the price of the underlying and computed it using Monte Carlo simulations in order to evaluate the corresponding locally risk neutralized valuation relationship (LRNVR) expectation. Other approaches for computing this hedge ratio include the finite difference method proposed by Engle and Rosenberg (1995), or the adjusted Black Scholes delta hedging computations based on analytic approximations of GARCH option prices, (see e.g. Choi (2005)). Kallsen and Taqqu (1998) proposed a continuous time GARCH process under which the associated markets are complete and also investigated hedging in the Black-Scholes sense. Duan’s (1995) definition of the delta hedge has been subjected to criticisms, the most important coming from Garcia and Renault (1999) who pointed out that this specification ignores the fact that the option price depends also on the conditional variance, which is itself a function of the asset price. They showed that when the option price is homogeneous of degree one with respect to the asset price and the strike price, then the option delta hedge is consistent with Duan’s formulation. Further discussions on homogeneity of option prices and delta hedging for scale-invariant models are provided in Bates (2005) and Alexander and Nogueira (2007a; 2007b). In order to take into account the stochastic volatility environment of GARCH models, Engle and Rosenberg (2000) considered the computation of the option’s deltas and gammas using the chain rule and studied the differences in empirical performance when hedging options with changing variance term structure for different volatility specifications.

The techniques briefly described above try to extend the hedging designed for complete markets to a GARCH context and, therefore, are not optimal in the incomplete market setting, that is, the use of continuous time hedging ratios for discrete-time models may generate additional hedging errors. Thus, various other hedging techniques have been proposed in the financial literature by minimizing different measures for the hedging error. One of the most influential strategies in this direction has been the local risk minimization scheme introduced by Föllmer, Schweizer, and Sondermann (see (1986; 1991; 2001), and references therein); this approach uses the notion of sequential regressions in order to construct a generalized trading strategy, not necessarily self-financing, which minimizes daily squared hedging errors. Local risk minimization is particularly convenient in the discrete time framework because it is well adapted to recursive algorithmic implementations and can be tuned to minimize
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hedging errors related to arbitrarily prescribed hedging frequencies. The standard approach for constructing local risk minimization hedges is to minimize the conditional expected value of the quadratic cost of hedging under the historical probability measure. This optimization procedure also gives rise to a contingent claim price computed in the risk neutral world with the well-known minimal martingale measure. Although local risk minimization has been widely used for pricing and hedging financial derivatives based on continuous time models, its implementation in discrete-time, and in particular for GARCH models, raises some issues. For example, in Ortega (2012) it has been shown that in the GARCH context the minimal martingale measure is signed, and it is only under very restrictive hypotheses, (the model innovations are required to be bounded), that option prices arising from local risk minimization using the physical measure are guaranteed to be arbitrage free. Additionally, a number of situations have been identified, (see e.g. Černý and Kallsen (2007)), in which the local minimization of squared hedging errors does not guarantee the minimization of the final unconditional expected squared hedging error; this point has motivated recent important work which targets the minimization of the global hedging risk, (see e.g. Černý and Kallsen (2007; 2008; 2009)). Therefore, one has to consider local quadratic minimization in a different context.

In this paper we provide a unified framework for local risk minimization and the standard minimum variance delta hedges for a general class of asymmetric non-Gaussian GARCH models. Firstly, we introduce local risk minimization with respect to a martingale measure for different hedging frequencies under a GARCH model with an unspecified distribution for the driving noise. When local risk minimization is carried out with respect to a martingale measure, a number of interesting features arise. For example, the option prices that result from the scheme are guaranteed to be arbitrage free and the hedging strategies in this case minimize, not only the local but also the global hedging risk. Additionally, there is a decoupling between the expressions that determine hedges and prices which can be taken advantage of in order to create numerically performing schemes to compute them.

An intuitive explanation behind risk neutral optimization and references to other research studies which undertake this approach are presented in Cont et al. (2007). To our knowledge, the only attempts at exploring local risk minimization in a GARCH setting are due to Ortega (2012) and Huang and Guo (2012). The former investigates the use of the local risk minimization with respect to a martingale measure in the context of Gaussian driven GARCH processes and shows how Duan (1995) and Heston and Nandi’s (2000) pricing formulas can be recovered in this fashion, while the latter investigates the risk adjusted expected quadratic cost of hedging minimal hedging strategies in the sense of Elliott and Madan (1998).

When the time between two consecutive observations approaches zero, we show that the local risk minimization hedge ratio under a martingale measure can be approximated with a stochastic volatility type delta hedge. More specifically, the resulting delta consists of the sum of the option delta (the first partial derivative of the option price with respect to the spot price) and the option vega (the first partial derivative of the option price with respect to the conditional variance process) scaled by a so called vega multiplier. The name of this term is borrowed from Engle and Rosenberg (2000). However, this approximation is different to the one proposed in that paper since all our Greeks and vega multipliers are computed directly based on a GARCH model rather than on an adjusted Black-Scholes price in the sense of Hull and White (1987). Using the extended Girsanov principle of
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Elliott and Madan (1998) we derive simplified expressions for these quantities under the general non-Gaussian framework, although the explicit computation of Greeks involves Monte Carlo simulation. This result generalizes the static delta hedge proposed by Duan (1995). In fact, the latter appears as a particular case of the one that we propose if changes in asset prices and conditional variances are uncorrelated. Finally we derive the local risk minimizing hedges under the non-GARCH diffusion limits of our model and show their relationships with our proposed discrete-time counterparts. This result also serves as a further justification of why Duan’s (1995) hedge is the correct instantaneous delta hedge only under the aforementioned assumption.

We provide an extensive numerical example in which we test the out-of-sample empirical performance of the proposed delta hedges for a special case of GARCH model driven by Normal Inverse Gaussian distributed innovations to hedge a collection of European call options on the S&P 500 index. The GARCH model parameters are estimated using maximum likelihood based on the historical returns of the underlying S&P 500 index. The benchmark hedge ratio used in our analysis is the ad hoc Black Scholes model proposed by Dumas et al. (1998). Our results show that overall both the local risk minimization strategy and its delta approximation outperform the ad hoc Black-Scholes benchmark. A detailed analysis of the hedging errors is provided for different groups of moneyness and times to maturity. Finally, we test the sensitivity of the schemes that we propose with respect to the choice of the pricing measure by using an exponential affine stochastic discount factor. As a result, we see that this other martingale measure leads to similar hedging performances and that there are no significant differences between the results obtained with the two pricing kernels.

The rest of the paper is organized as follows. Section 2 discusses local risk minimization with respect to the physical and risk neutral measures, and their relationship with minimum variance hedging. In Section 3 we compute quadratic hedges for general discrete time GARCH models and their diffusion limits. Section 4 investigates the empirical performance of the proposed GARCH hedges using both asset returns and option data. Section 5 concludes the paper.

2 Local risk minimization for GARCH options

Consider a discrete time financial market with the set of trading dates indexed by \( \mathcal{T} = \{ t | t = 0, \ldots , T \} \). The market consists of one reference asset \( S_0 \) and one risky asset \( S \). We denote by \( P \) the underlying probability measure and we assume that the dynamics of these assets are modeled by the following bivariate stochastic process \( (S_0, S) = \{ (S_{t}, S_t) \}_{t \in \mathcal{T}} \). The risk-free asset is assumed to follow a deterministic process and it evolves over time according to the following equation:

\[
S_0^t = e^{rt}, \quad S_0^0 = 1. \tag{2.1}
\]

Here \( r \) represents the instantaneous risk free rate of return. The log-return on the risky asset process, denoted by \( y = \{ y_t \}_{t \in \mathcal{T}} := \{ \ln (S_t/S_{t-1}) \}_{t \in \mathcal{T}} \), has a general asymmetric GARCH(1,1) structure (NGARCH) with the
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\[ y_t = \mu_t + \sigma_t \epsilon_t, \quad \epsilon_t | \mathcal{F}_{t-1} \sim D(0,1), \quad (2.2) \]
\[ \sigma_t^2 = \alpha_0 + \alpha_1 \sigma_{t-1}^2 \omega(\epsilon_{t-1}) + \beta_1 \sigma_{t-1}^2. \quad (2.3) \]

The uncertainty modeled through the complete probability space \((\Omega, \mathcal{F}, P)\) has a filtration \(\mathcal{F}_t := \{ \mathcal{F}_t \}_{t \in T}\), where \(\mathcal{F}_t\) represents the \(\sigma\)-field of all market information available up to time \(t\). The innovations \(\{\epsilon_t\}_{t \in T}\) is a sequence of random variables such that for each \(t\), \(\epsilon_t\) is independent and identically distributed conditional on \(\mathcal{F}_t\) with a standardized distribution \(D(0,1)\) under \(P\). We assume that the innovations conditional cumulant generating function exists in a neighborhood of zero, that is:
\[ \kappa_{\epsilon_t}(z) = \ln E_P [e^{z \epsilon_t}] < \infty, \quad z \in (-u, u), \quad u > 0. \]

The conditional mean log-return \(\mu_t\) is \(\mathcal{F}_{t-1}\) measurable. A specific form in the spirit of Christoffersen et al. (2009) will be used starting in the following section. The conditional variance equation has a GARCH(1,1) structure with a news impact curve modeled through the function \(\omega(\cdot)\). Our theoretical and numerical results in the next sections will be derived based on an asymmetric NGARCH structure. Finally, the parameters are assumed to satisfy the standard second order stationarity conditions. It is well known that, in the absence of arbitrage, the price of any contingent claim can be expressed as the discounted expected value of its payoff at maturity under a \(P\)-equivalent risk neutral probability measure. Since the market implied by GARCH models is incomplete, there exists an infinite number of such pricing measures. In order to conclude the characterization of our GARCH(1,1) pricing model we need to specify the risk neutralized dynamics of the log-returns under such a measure. Thus, we propose below the following general GARCH(1,1)-type structure for the log-return process under a martingale measure generically denoted by \(Q\):
\[ y_t = r - \kappa_{\epsilon_t}^*(\sigma_t^2) + \sigma_t \epsilon_t^*, \quad \epsilon_t^* | \mathcal{F}_{t-1} \sim D^*(0,1) \quad (2.4) \]
\[ \sigma_t^{*2} = \alpha_{0t}^* + \alpha_{1t}^* \sigma_{t-1}^{*2} \omega^*(\epsilon_{t-1}^*) + \beta_{1t}^* \sigma_{t-1}^{*2}. \quad (2.5) \]

The above dynamics provide us with a general GARCH characterization in the risk neutral world. This structure nests some of the most popular martingale measures used in the GARCH option pricing literature. In particular, the extended Girsanov principle and the exponential affine discount factors can be viewed as special cases of (2.4)-(2.5). All risk neutral quantities are illustrated through a “\(^*\)” notation, so that \(\sigma_t^{*2}\) represents the risk neutral conditional variance of the log-return process, while \(\kappa_{\epsilon_t}^*(\cdot)\) is the \(\mathcal{F}_{t-1}\)- conditional cumulant generating function of \(\epsilon_t^*\) under \(Q\). The standard innovation process under the martingale measure is assumed to have a conditional distribution \(D^*(0,1)\) under the martingale measure that is in general different from \(D(0,1)\). However, in many practical examples \(D^*\) and \(D\) coincide. Notice that the GARCH-type parameters may no longer be constants under the new measure. However, in order to keep the predictability structure of the conditional variance under \(Q\), we
assume that $\alpha^*_0$, $\alpha^*_1$, and $\beta^*_1$ are all $\mathcal{F}_{t-1}$ measurable.

2.1 Local risk minimization with respect to the physical measure

Since the market associated with GARCH modeled assets is incomplete, there exist contingent products that cannot be fully replicated using a self-financing portfolio made out of its underlying and a bond. A number of techniques have been developed over the years that tackle simultaneously the pricing and hedging problems by replacing the concept of replication with that of hedging efficiency. As we shall see, these techniques provide both expressions for prices and hedging ratios which, even though they require in most cases Monte Carlo computations, admit convenient interpretations based on the notion of hedging error minimization that can be adapted to various models for the underlying asset. In the following paragraphs we briefly describe the $P$-local risk minimization strategy for hedging a European contingent claim $H$ that depends on the terminal value of the risky asset $S_t$.

A generalized trading strategy is a pair of stochastic processes $(\xi^0, \xi^1)$ such that 

$${\xi^0}_t \in \{0, \ldots, T\}$$

is adapted and 

$${\xi^1}_t \in \{1, \ldots, T\}$$

is predictable. The associated value process $V$ of $(\xi^0, \xi^1)$ is defined as

$$V_0 := {\xi^0}_0, \quad \text{and} \quad V_t := {\xi^0}_t \cdot S_0 + {\xi^1}_t \cdot S_t, \quad t = 0, \ldots, T.$$ 

The cost process $C$ corresponding to this strategy is defined by:

$$C_t := V_t - \sum_{k=1}^{t} {\xi^1}_k \cdot (S_k - S_{k-1}), \quad t = 0, \ldots, T.$$ 

The locally risk minimization hedging strategy optimizes the following risk process:

$$LR_t(\xi^0, \xi) := E^P \left[ (\tilde{C}_{t+1} - \tilde{C}_t)^2 \mid \mathcal{F}_t \right], \quad t = 0, \ldots, T - 1.$$ 

Here $\tilde{C}_t$ is the discounted cost price at time 0, $\tilde{C}_t = C_t e^{-rt}$. It has been showed that, whenever a local risk-minimizing technique exists, it is fully determined by the backwards recursions:

$$V_T = H, \quad (2.6)$$

$$\xi^P_{t+1} = \frac{\text{Cov}^P (\tilde{V}_{t+1}, \tilde{S}_{t+1} - \tilde{S}_t \mid \mathcal{F}_t)}{\text{Var}^P (\tilde{S}_{t+1} - \tilde{S}_t \mid \mathcal{F}_t)}, \quad (2.7)$$

$$\tilde{V}_t = E^P \left[ \tilde{V}_{t+1} \mid \mathcal{F}_t \right] - \xi^P_{t+1} E^P \left[ \tilde{S}_{t+1} - \tilde{S}_t \mid \mathcal{F}_t \right]. \quad (2.8)$$

The upper script in the hedging ratio formula (2.7) indicates that the solution is obtained by minimizing the local risk under $P$. An appealing feature of local risk minimization consists of its adaptivity to prescribed changes in the hedging frequency. Indeed, without any loss of generality we suppose that the life of the option $H$ with maturity in $T$ time steps is partitioned into identical time intervals of duration $j$; this assumption implies the existence of an integer $k$ such that $kj = T$. We now wish to set up a local risk minimizing replication strategy for $H$ in which
hedging is carried out once every \( j \) time steps. We shall denote by \( \xi_{t+j} \) the hedging ratio at time \( t \) that presupposes that the next hedging will take place at time \( t + j \). The value of such ratios will be obtained by minimizing the \( j \)-spaced local risk process:

\[
LR_t^{(j)}(\xi, \xi) := \mathbb{E}^P \left[ (\bar{C}_t^{(j)} - \bar{C}_t^{(j)})^2 \mid \mathcal{F}_t \right], \quad t = 0, j, 2j, \ldots, (k-1)j = T - j.
\] (2.9)

Here \( \{\bar{C}_t^{(j)}\} \) is the cost process associated with this type of strategy. A convoluted but straightforward induction argument shows that the \( j \)-step local risk minimization is the solution of the following backward recursions:

\[
V_T^{(j)} = H,
\]

\[
\xi_{t+j}^P = \frac{\text{Cov}^P(e^{-rT}H \cdot N_T \cdot N_{t+j} \cdots N_{t+j}, S_t^{(j)} - S_t^{(j)} \mid \mathcal{F}_t)}{\text{Var}^P[S_{t+j} - S_t \mid \mathcal{F}_t]},
\]

\[
\tilde{V}_t^{(j)} = \mathbb{E}^P[e^{-rT}H \cdot N_T \cdot N_{t+2j} \cdot S_{t+j} - S_t \mid \mathcal{F}_t], \quad t = 0, j, 2j, \ldots, T - j,
\] (2.12)

Here, for any \( t = j, 2j, \ldots, T \), the process \( N_t \) is given by:

\[
N_t = \frac{1 - \gamma_t(\bar{S}_t - \bar{S}_{t-j})}{\mathbb{E}^P[1 - \gamma_t(\bar{S}_t - \bar{S}_{t-j}) \mid \mathcal{F}_{t-j}]} = 1 - \frac{\mathbb{E}^P[\bar{S}_t - \bar{S}_{t-j} \mid \mathcal{F}_{t-j}] \left( \bar{S}_t - \mathbb{E}^P[\bar{S}_t \mid \mathcal{F}_{t-j}] \right)}{\text{Var}^P[\bar{S}_t - \bar{S}_{t-j} \mid \mathcal{F}_{t-j}]},
\] (2.13)

where,

\[
\gamma_t = \frac{\mathbb{E}^P[\bar{S}_t - \bar{S}_{t-j} \mid \mathcal{F}_{t-j}]}{\mathbb{E}^P[(\bar{S}_t - \bar{S}_{t-j})^2 \mid \mathcal{F}_{t-j}]}.
\]

When the product \( Z_T := \prod_{t \in \{j, 2j, \ldots, T\}} N_t \) is a positive random variable, the relation \( Z_T := dQ^{\text{min}} / dP \) defines a measure equivalent to \( P \), called the minimal martingale measure, for which the discounted partial process \( \{\bar{S}_j, \bar{S}_{2j}, \ldots, \bar{S}_T\} \) is a martingale. The interest of this measure is that, when it exists and in the case \( j = 1 \), the value process of the local risk-minimizing strategy with respect to the physical measure coincides with the arbitrage free price for \( H \) obtained by using \( Q^{\text{min}} \) as a pricing kernel.

There are various implementation issues for the recursions (2.10)–(2.12) that need to be taken care of when asset returns are modeled by GARCH processes; we analyze in detail some of them in the next section where we also propose an alternative hedging scheme.

### 2.2 Local risk minimization with respect to a martingale measure

The minimal martingale measure is usually a signed measure in a discrete time setting, so derivative valuation based on this approach might not be suitable. For example, the Radon-Nikodym process defined in (2.13) can take negative values and this may lead to negative prices when computing the expectations from (2.12) using Monte Carlo simulation. For asset returns governed by GARCH models, one can impose conditions on the parameter set or the innovations which can be too restrictive and make the estimation more challenging. A sufficient condition
in the GARCH context requires the driving noise to take bounded values (see, for example, Ortega (2012)).

The recursive derivation of a derivative price according to (2.10)-(2.12) is not an easy task even in settings when the minimal martingale measure is a probability measure. Both the option prices and hedging ratios computations require the use of Monte Carlo simulations under the physical measure $P$. An inspection of the expressions (2.10)–(2.12) shows that in order to compute them we need first an estimation of the stochastic discount factors $\{N_j, \ldots, N_T\}$. When $j > 1$ this estimation is necessarily conducted using Monte Carlo simulations whose results are in turn substituted in the expressions (2.10)–(2.12) which are also evaluated using Monte Carlo. The variance of the resulting estimator is too high and makes the results unacceptable. Moreover, the option prices that result from this technique cannot be interpreted as arbitrage free prices if the hedging frequency is lower than periods at which asset prices are observed. Indeed, in the case $j > 1$, the resulting measure is a martingale measure for the discounted partial process $\{\tilde{S}_j, \tilde{S}_2, \ldots, \tilde{S}_T\}$ but not for the entire discounted price process $\{\tilde{S}_1, \tilde{S}_2, \ldots, \tilde{S}_T\}$ and therefore there is a possibility for arbitrage.

As described in Basak and Chabakauri (2012), another potential problem with variance minimizing hedging strategies is its time-inconsistency. These authors argue that can be avoided by either supposing the market is complete or by assuming a zero risk premium for the asset return. The former clearly does not fit our GARCH setting while the latter is equivalent to the discounted asset price being a martingale under the physical measure; hence, one way to overcome the time-inconsistency problem is to consider hedging directly under a risk neutral measure.

The reasons that we mentioned above lead us to explore the local risk minimization strategy for martingale measures, despite the fact that the historical probability associated with the price process represents a more natural approach from a risk management perspective. We derive below recursive pricing and hedging relations using risk minimization under risk-neutral measures. These are obtained in a straightforward manner using expressions (2.10)–(2.12) combined with the martingale hypothesis in its statement which makes the stochastic discount factors (2.13) $\{N_t\}_{t \in \{j, 2j, \ldots, T\}}$ automatically all equal to 1.

**Proposition 2.1** Let $Q$ be an equivalent martingale measure for the price process $\{S_t\}$ and let $H(S_T)$ be a European contingent claim which depends on the terminal value of the risky asset $S_t$. The locally risk minimizing strategy every $j$ time steps with respect to the measure $Q$ is determined by the recursions:

$$V_T^{(j)} = H,$$

$$\xi_{t+j}^Q = e^{-r(T-t)} \frac{E^Q[H(S_T)(S_{t+j}e^{-rj} - S_t) | F_t]}{\text{Var}^Q[S_{t+j}e^{-rj} - S_t | F_t]},$$

$$V_t^{(j)} = E^Q\left[e^{-r(T-t)}H(S_T) | F_t\right],$$

for all $t = 0, j, 2j, \ldots, T - j$.

For daily hedging ($j = 1$), the denominator of (2.15) can be explicitly written down in terms of the $F_t$-conditional
cumulant generating function of $\epsilon^*_{t}$ under $Q$ and of the risk neutral conditional variance $\sigma^*_{t}$. However, for lower hedging frequencies ($j > 1$) this denominator needs to be evaluated by using the Monte Carlo estimator for the variance.

The recursion formulas require further explanation. First, local risk minimization under a martingale measure does not directly determine the arbitrage free price as in the historical probability optimization case. The option price is, a priori, established by assuming that the discounted value process is a martingale under $Q$; (2.16) serves as a verification of this fact. The value process $V^{(j)}_{t}$ is the same for any $j$, so it does not depend on the hedging frequency. $V_0$ represents the necessary initial investment to construct the local minimizing strategy to replicate $H$. This coincides with the arbitrage free pricing for the payoff $H$ and it depends on the choice of the pricing kernel $Q$.

Secondly, the hedging ratios in (2.15) can be computed using standard Monte Carlo techniques by simulating asset price paths under the considered risk neutral measure. In cases where simulation under $Q$ is not very convenient, one can compute both the numerator and the denominator of (2.15) by simulating price paths together with the corresponding Radon-Nikodým derivative. Note that if $Q$ is chosen to be the minimal martingale measure, the discounted value processes from (2.12) and (2.16) coincide, while their corresponding hedging ratios are different. When $Q$ is the pricing measure given by the extended Girsanov principle, the hedging scheme from (2.1) is the same as the one obtained in Elliott and Madan (1998) by minimizing the expected discounted risk adjusted squared costs of hedging under the historical measure. Finally, the optimal hedge ratios from (2.15) minimize the conditional remaining risk and the global risk, since these criteria are equivalent under a martingale measure. Thus, these strategies are also variance optimal.

3 Local risk minimization and GARCH diffusion approximations

In this section we derive two types of hedging ratios for GARCH options. Firstly, using an idea inspired by a continuous time approach, we derive local risk minimization hedges based on the assumption that hedging is performed at the same frequency as the underlying is observed and that the time between observations is small. We then compute locally risk minimizing delta hedges for non-Gaussian GARCH diffusion limits and show the relationship with their discrete time counterparts.

Proposition 3.1 Let $H$ be a European contingent product on the underlying price process $\{S_t\}_{t \in T}$ generated by a GARCH model. Let $\Pi_t^{Q^\text{min}} = \Pi_t^{Q^\text{min}}(S_t, \sigma^2_{t+1}) = E^{Q^\text{min}}[e^{r(T-t)}H | F_t]$ and $\Pi_t^{Q} = \Pi_t^{Q}(S_t, \sigma^2_{t+1}) = E^{Q}[e^{r(T-t)}H | F_t]$ be associated arbitrage free prices obtained by using the minimal martingale measure $Q^\text{min}$ and another arbitrary pricing measure $Q$, respectively. If the time between two consecutive observations approaches zero, the following relations hold:

1. The local risk minimization hedge under $P$ can be approximated by:

$$\xi_{t+1}^P \approx \Delta_{t+1}^{Q^\text{min}} + VM_{t+1}^P \Delta_{t+1}^{Q^\text{min}}. \tag{3.1}$$
Here $\Delta_{t,S}^{Q_{\text{min}}} = \frac{\partial \Pi_{Q_{\text{min}}}}{\partial S_t}$ and $\Delta_{t,\sigma^2}^{Q_{\text{min}}} = \frac{\partial \Pi_{Q_{\text{min}}}}{\partial \sigma_{t+1}^2}$ are the sensitivity of the minimum martingale option price with respect to the asset price and to its conditional variance, respectively. $VM_{t+1}^P$ is the vega multiplier under $P$ given by:

$$VM_{t+1}^P = \frac{\text{Cov}^P (S_{t+1} - S_t, \sigma_{t+1}^2 - \sigma_t^2) | \mathcal{F}_t)}{\text{Var}^P [S_{t+1} - S_t | \mathcal{F}_t]}.$$ (3.2)

(ii) The local risk minimization hedge under $Q$ can be approximated by:

$$\xi_{t+1}^Q \approx \Delta_{t,S}^{Q} + VM_{t+1}^Q \Delta_{t,\sigma^2}^{Q}.$$ (3.3)

Here $\Delta_{t,S}^{Q} = \frac{\partial \Pi_{Q}}{\partial S_t}$ and $\Delta_{t,\sigma^2}^{Q} = \frac{\partial \Pi_{Q}}{\partial \sigma_{t+1}^2}$ are the sensitivity of the minimal martingale measure option price with respect to the asset price and to its conditional variance, respectively. $VM_{t+1}^Q$ is the vega multiplier under $Q$ given by:

$$VM_{t+1}^Q = \frac{\text{Cov}^Q (S_{t+1} - S_t, \sigma_{t+1}^2 - \sigma_t^2) | \mathcal{F}_t)}{\text{Var}^Q [S_{t+1} - S_t | \mathcal{F}_t]}.$$ (3.4)

The above results can also be obtained using standard minimum variance techniques. The resulting strategies are called minimum variance hedging ratios and have been investigated in both complete and incomplete continuous-time settings (see, for example, Boyle and Emanuel (1980), Bakshi at al. (1997) and Alexander and Nogueira (2007a) among others). Indeed, if we consider a delta-neutral portfolio consisting of a long position on a unit of the derivative product and a short one on $\xi_t$ units of the underlying, we can decide on the quantity which should be invested in the underlying asset by minimizing the one-step ahead portfolio variance. Note that in this case the option price needs to be predetermined based on a pricing measure since this approach provides a criterion only for the selection of the optimal hedge and not for both the price and the hedge. In our case, (3.1) is obtained by minimizing the portfolio variance under $P$ with the option price given by the minimal martingale measure, while (3.3) is found from the same minimization problem under the risk neutral measure $Q$ used to compute the option price. In fact, “optimal” solutions similar to (3.3) can be further constructed for any given probability measure, the vega multiplier being the only quantity which changes with respect to this choice.

The hedging approximation in (3.3) can be viewed as a correction of the so called static delta hedge proposed by Duan (1995), according to which the hedge ratio is the partial derivative of the option price with respect to the underlying. This hedge coincides with those proposed in Proposition 3.1 only when either changes in assets and conditional variances are uncorrelated under $Q$, or when $\Delta_{t,\sigma^2}^{Q} = 0$ which is not consistent with the GARCH setting. Indeed, as García and Renault (1999) pointed out, Duan’s (1995) result ignores the fact that the option price in the GARCH context depends on the conditional variance, which is itself a function of the asset price. Using this argument, one more approximation of $\xi_t$ can be obtained if we use:

$$\sigma_{t+2}^2 - \sigma_{t+1}^2 \approx \frac{d\sigma_{t+1}^2}{dS_t} (S_{t+1} - S_t).$$
In this case the vega multiplier, under both P or Q, becomes $\Delta V_M = d\sigma_t^2/dS_t$, and, therefore, resembles a total
derivative formula for the option price with respect to the asset price.\textsuperscript{7} Engle and Rosenberg (2000) proposed
the use of a total derivative formula for hedging discrete time stochastic volatility options. However, instead
of computing the Greeks based directly on GARCH implied option prices, their approach was based on a Hull
and White (1987) Black-Scholes substitution type formula and a vega multiplier based on the average expected
volatility.

### 3.1 Semi-explicit solutions under the extended Girsanov principle

The goal of this section is to provide a semi-explicit solution for the above local risk minimizing hedging approx-
imation in a general GARCH setting. Since the minimal martingale measure is signed, we focus only on deriving
an expression for $\xi_Q^t$ in (3.3) for a special choice of $Q$. More specifically, we shall consider the extended Girsanov
principle as our pricing measure candidate. Firstly, we need to describe our models under the physical and risk
neutral measures. As we announced above, we now assume a special parametrization for the conditional mean
return and the news impact curve. The dynamics under $P$ are given by:

$$
\begin{align*}
  y_t &= r + \lambda \sigma_t - \kappa \epsilon_t^*(\sigma_t) + \sigma_t \epsilon_t, \quad \epsilon_t | F_{t-1} \sim D(0,1), \\
  \sigma_t^2 &= \alpha_0 + \alpha_1 \sigma_{t-1}^2 (\epsilon_{t-1} - \gamma)^2 + \beta_1 \sigma_{t-1}^2.
\end{align*}
$$

Here $\lambda$ quantifies the market price of risk per unit volatility and $\gamma$ is the leverage effect parameter. When $D(0,1)$ is
a standard Gaussian distribution, we have that $\kappa^P_t(\sigma_t) = \sigma_t^2/2$, and hence the return dynamics in (3.5) are identical
to those in Duan (1995). The basic principle behind the construction of the extended Girsanov principle relies on
changing the conditional mean return distribution so that the conditional variance remains unchanged under the
new probability measure, denoted here by $Q^{egp}$. This translates into the following risk-neutral representation for
the asset returns:

$$
\begin{align*}
  y_t &= r - \kappa \epsilon_t^* (\sigma_t) + \sigma_t \epsilon_t^*, \quad \epsilon_t^* \sim D(0,1), \\
  \sigma_t^2 &= \alpha_0 + \alpha_1 \sigma_{t-1}^2 (\epsilon_{t-1} - \lambda - \gamma)^2 + \beta_1 \sigma_{t-1}^2.
\end{align*}
$$

Since the conditional law of $\epsilon_t$ under $P$ is the same as that of $\epsilon_t^*$ under $Q^{egp}$, it is straightforward to verify that the
discounted asset prices process is a martingale under $Q^{egp}$. Equations (3.7)-(3.8) generalize the local risk neutral
valuation relation to non-Gaussian GARCH models. We now write down two expressions that we shall need in
deriving the Greeks of a European call option which uses the above GARCH model for the underlying asset. Firstly,
using (3.7)-(3.8), the time evolution of the prices under $Q^{egp}$ is given by

$$
S_T = S_t e^{r(T-t) - \sum_{i=t+1}^{T} \kappa_i \epsilon_{i}(\sigma_i) + \sum_{i=t+1}^{T} \sigma_i \epsilon_i^*}.
$$
Secondly, we let:

$$P_i := \alpha_1 (\epsilon_i^* - \lambda - \gamma)^2 + \beta_1, \quad i = 0, \ldots, T.$$ 

A straightforward induction argument using (3.8) implies that:

$$\sigma^2_s = \alpha_0 A(s, l) + \sigma^2_l B(s, l) \quad \text{with} \quad l = 0, \ldots, T - 1 \quad \text{and} \quad s > l,$$

where the coefficients are given by:

$$A(s, l) := \prod_{i=l}^{s-1} P_i \left[ \sum_{k=l}^{s-1} \frac{1}{\prod_{i=k}^{l-1} P_i} \right] \quad \text{and} \quad B(s, l) := \prod_{i=l}^{s-1} P_i. \quad (3.10)$$

**Proposition 3.2** For a European call option with strike price $K$ which has (3.7)-(3.8) as the risk-neutralized log-returns generating process, the quantities needed to compute the $Q^{egp}$-locally risk minimization hedging strategy in (3.3) are given by:

$$\Delta_{Q^{egp}} t, S = e^{-r(T-t)} E^{Q^{egp}} \left[ \frac{S_T}{S_t} 1_{\{S_T > K\}} \mid \mathcal{F}_t \right], \quad (3.11)$$

$$\Delta_{Q^{egp}} t, \sigma^2 = \frac{e^{-r(T-t)}}{2} E^{Q^{egp}} \left[ S_T \sum_{t+1}^{T-l} B(t + l, t + 1) \frac{(\epsilon_{t+l}^* - \kappa_{t+l}^* (\sigma_{t+1}))}{\sigma_{t+l}} 1_{\{S_T > K\}} \mid \mathcal{F}_t \right], \quad (3.12)$$

$$VM_{t+1}^{Q^{egp}} = \frac{\alpha_1 \sigma_{t+1}^2}{e^s S_t} \left( \kappa_{t+1}^* (\sigma_{t+1}) \right)^2 - \frac{2(\lambda + \gamma) \kappa_{t+1}^* (\sigma_{t+1}) + \kappa_{t+1}^* (\sigma_{t+1}) - 1}{e^{\kappa_{t+1}^* (2\sigma_{t+1}) - 2\kappa_{t+1}^* (\sigma_{t+1}) - 1}}. \quad (3.13)$$

Here $B(\cdot, \cdot)$ is given by (3.10) with the convention $B(t + 1, t + 1) := 1$.

Equation (3.11) resembles the formula derived in Duan (1995) for Gaussian GARCH models. This relation also holds for any type of asset return process with a general GARCH risk-neutralization of the type given in (2.4)-(2.5). Formula (3.12) provides a general representation for the option vega under a non-Gaussian GARCH model risk-neutralized via the extended Girsanov principle. When the innovations are Gaussian, this expression reduces to the one given in Duan (2000) for an asymmetric GARCH model.\(^8\) Since no closed form results are available for the conditional expectations in (3.11) and (3.12), we use Monte Carlo simulations to evaluate them. The vega multiplier is expressed in closed-form in (3.13) and it depends on the first and second derivatives of the conditional cumulant generating function of the driving noise. A much simpler expression for $VM_t$ can be obtained if one wishes to use the total derivative formula for the hedging ratio in (3.3). In this case, the vega multiplier becomes,

$$VM_{t+1} = d\sigma_{t+1}^2/dS_t = 2\alpha_1 \sigma_t (\epsilon_t - \gamma)/S_t.$$ 

We shall not illustrate numerical results based on that expression. Instead, our aim is to investigate the empirical performance of the delta hedge from (3.11) and the $Q$-local risk minimizing strategy from (3.3) based on the quantities derived in Proposition 3.2.

\(^8\)The option vega for a GARCH European Call option was given in Duan (2000) without proof or further numerical implementation.
3.2 Local risk minimization for non-Gaussian GARCH diffusion models

In this section we investigate the local risk minimization hedging strategies within the class of stochastic volatility models which are obtained as weak limits of non-Gaussian GARCH models under both the underlying and risk-neutralized measures. Furthermore, we study their relations with the minimum variance hedges derived in Proposition 3.1.

The weak convergence of GARCH models to bivariate diffusions, where the volatility process and the price process are uncorrelated, was first studied by Nelson (1990) and further extended by Duan (1997) for a more general class of augmented GARCH models, which nests the most commonly used GARCH frameworks in the literature. These convergence results are typically based on a set of arbitrary assumptions on the model parameters. Since the bivariate diffusion limits of GARCH models proposed by Nelson (1990) and Duan (1997) are of widespread use for pricing and hedging derivatives in the continuous time setting, we restrict our attention to the assumptions in those references. In particular, our results are based on the non-Gaussian GARCH diffusion limits derived in Badescu et al. (2013) based on the extended Girsanov principle.

Firstly, we consider a finer discretization of the model from (3.5)-(3.6) by dividing the interval \([0, \ldots, T]\) into \(nT\) equally spaced points of length \(h = 1/n\) and indexed by \(k, k = 1, 2, \cdots, nT\). The log-price process has the following representation on the probability space \((\Omega, \mathcal{F}, \{\mathcal{F}_{kh,n}\}_{k=0, \ldots, nT}, P_n)\):

\[
\ln S_{kh,n} - \ln S_{(k-1)h,n} = \left( r + \lambda \sigma_{kh,n} - \kappa \epsilon_{kh,n} (\sigma_{kh,n}) \right) h + \sqrt{h} \sigma_{kh,n} \epsilon_{kh,n}, \quad \epsilon_{(k+1)h,n} \sim \mathcal{D}(0,1) \tag{3.14}
\]

\[
\sigma_{(k+1)h,n}^2 - \sigma_{kh,n}^2 = \alpha_0(h) + \alpha_1(h) \sigma_{kh,n}^2 (\epsilon_{kh,n} - \gamma(h))^2 + (\beta_1(h) - 1) \sigma_{kh,n}^2. \tag{3.15}
\]

Here, \(\epsilon_{kh,n}\) are i.i.d. \(\mathcal{D}(0,1)\)-distributed random variables. We denote by \(M_j\) the raw moments of \(\epsilon_{kh,n}\). Note that when \(h = 1\), the above equations reduce to the NGARCH(1,1) model in (3.5)-(3.6). Using the following parametric constraints:

\[
\lim_{h \to 0} \frac{\alpha_1(h)}{h} = \omega_0, \quad \lim_{h \to 0} \frac{1 - \beta_1(h) - \alpha_1(h) (1 + \gamma^2(h))}{h} = \omega_1, \quad \lim_{h \to 0} \frac{\alpha_2(h)}{h} = \omega_2, \quad \lim_{h \to 0} \gamma(h) = \omega_3, \tag{3.16}
\]

Badescu et al. (2013) showed that when \(h\) approaches zero the process from (3.14)-(3.15) converges weakly to the following bivariate diffusion process:

\[
dS_t = \left( r + \lambda \sigma_t + \frac{1}{2} \sigma_t^2 - \kappa \epsilon_t (\sigma_t) \right) S_t dt + \sigma_t S_t dW_{1t}, \tag{3.17}
\]

\[
d\sigma_t^2 = \left( \omega_0 - \omega_1 \sigma_t^2 \right) dt + \sqrt{\omega_2} (M_3 - 2 \omega_3) \sigma_t^2 dW_{1t} + \sqrt{\omega_2} \sqrt{M_4 - M_3^2 - 1} \sigma_t^2 dW_{2t}. \tag{3.18}
\]

Here, \(W_{1t}\) and \(W_{2t}\) are two independent Brownian motions on \((\Omega, \mathcal{F}, \{\mathcal{F}_t\}_{t \in [0, \ldots, T]}, P)\). When the GARCH innovations are standard Gaussian distributed, the continuous time approximation from (3.17)-(3.18) coincides with the standard GARCH diffusion limit obtained in Duan (1997).
Applying the extended Girsanov transform to the discrete-time model given in (3.14)-(3.15) leads to the following risk-neutralized dynamics under \(Q_n^{gp}\):

\[
\ln S_{kh,n} - \ln S_{(k-1)h,n} = \left( r - \frac{1}{2} \kappa_{ekh,n} \left( \sqrt{h} \sigma_{kh,n} \right) \right) h + \sqrt{h} \sigma_{kh,n} \epsilon_{kh,n}^*, \quad \epsilon_{(k+1)h,n}^* \sim \mathcal{D}(0,1), \tag{3.19}
\]

\[
\sigma_{(k+1)h,n}^2 - \sigma_{kh,n}^2 = \alpha_0(h) + \alpha_1(h) \sigma_{kh,n}^2 \left( \epsilon_{kh,n}^* - \sqrt{h} \rho_{kh,n} - \gamma(h) \right)^2 + (\beta_1(h) - 1) \sigma_{kh,n}^2. \tag{3.20}
\]

Here, the driving noise process \(\{\epsilon_{kh,n}^*\}_{k=0,\ldots,nT}\) represents a sequence of independent random variables \(\mathcal{D}(0,1)\)-distributed under \(Q_n^{gp}\), which are related to the underlying innovations by \(\epsilon_{kh,n}^* = \epsilon_{kh,n} + \sqrt{h} \rho_{kh,n}\), where \(\rho_{kh,n}\) is the market price of risk given by:

\[
\rho_{kh,n} = \lambda + \frac{\frac{1}{2} \kappa_{ekh,n} \left( \sqrt{h} \sigma_{kh,n} \right) - \kappa_{ekh,n} \left( \sigma_{kh,n} \right)}{\sigma_{kh,n}}. \tag{3.21}
\]

Note that when \(h = 1\) the price of risk becomes \(\lambda\) and the above risk neutralized dynamics reduces to the one in (3.7)-(3.8). Badescu et al. (2013) showed that under the parametric constraints in (3.16), the discrete time process (3.19)-(3.20) weakly converges to the following stochastic volatility model:

\[
dS_t = rS_t dt + \sigma_t S_t dW_{1t}^*, \tag{3.22}
\]

\[
d\sigma_t^2 = (\omega_0 - (\omega_1 - 2 \sqrt{\omega_2 \omega_3 \rho_t}) \sigma_t^2) dt + \sqrt{\omega_2(M_3 - 2 \omega_3)} \sigma_t^2 dW_{1t}^* + \sqrt{\omega_2} \sqrt{M_4 - M_3^2 - 1} \sigma_t^2 dW_{2t}. \tag{3.23}
\]

Here, \(\rho_t\) is the continuous time limit of \(\rho_{kh,n}\) in (3.21) given by:

\[
\rho_t = \lambda + \frac{\frac{1}{2} \sigma_t^2 - \kappa_{e\sigma_t}(\sigma_t)}{\sigma_t}.
\]

The two Brownian motions \(W_{1t}^*\) and \(W_{2t}\) are independent of \(\left( \Omega, \mathcal{F}, \{\mathcal{F}_t\}_{t \in [0, \ldots, T]}, Q^{gp}\right)\) and \(dW_{1t}^* = dW_{1t} + \rho_t dt\) and \(dW_{2t}^* = dW_{2t} - \rho_t M_3/\sqrt{M_4 - M_3^2} - 1 dt\). When the innovations are standard Gaussian distributed, it follows that \(\rho_t = \lambda\) and thus the continuous time limit (3.22)-(3.23) coincides with the GARCH diffusion limit in Duan (1997). However, for skewed innovations (i.e. \(M_3 \neq 0\)), the continuous time implied extended Girsanov principle induces a non-zero market price of \(W_{2t}\) risk and the above risk-neutralized dynamics are no longer obtained by applying the the minimal martingale measure to the process (3.17)-(3.18), (that is, when \(dW_{2t}^* = dW_{2t}\)). Under this change of measure, the asset price dynamics are the same as in (3.22), but the risk-neutral conditional variance becomes:

\[
d\sigma_t^2 = (\omega_0 - (\omega_1 + \sqrt{\omega_2} (M_3 - 2 \omega_3) \rho_t) \sigma_t^2) dt + \sqrt{\omega_2} (M_3 - 2 \omega_3) \sigma_t^2 dW_{1t}^* + \sqrt{\omega_2} \sqrt{M_4 - M_3^2 - 1} \sigma_t^2 dW_{2t}. \tag{3.24}
\]

An interesting point is that the above limit (3.22)-(3.23) can be also obtained by applying the exponential affine change stochastic discount factor of Christoffersen et al. (2009) to the underlying GARCH model.

**Proposition 3.3** Suppose that the asset returns are governed by the stochastic volatility process determined by
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(3.17)-(3.18). Then the locally risk minimizing hedging strategies with respect to \( P \) and \( Q^{egp} \) are given by:

\[
\xi^P_t = \Delta^{Q^{min}}_{t,S} + \frac{\sigma_t}{\sqrt{\omega_2}} (M_3 - 2\omega_3) \Delta^{Q^{min}}_{t,\sigma^2}, \\
\xi^{Q^{egp}}_t = \Delta^{Q^{egp}}_{t,S} + \frac{\sigma_t}{\sqrt{\omega_2}} (M_3 - 2\omega_3) \Delta^{Q^{egp}}_{t,\sigma^2}.
\]

Here the above Greeks under \( Q^{egp} \) and \( Q^{min} \) are computed based on prices associated with asset returns from (3.22) and conditional variance dynamics from (3.23) and (3.24), respectively. The proof of Proposition 3.3 follows the same three steps procedure as in Poulsen et al. (2009); this is based on the algorithm proposed by El Karoui et al. (1997) according to which the market is first completed by introducing another tradable asset, then the delta hedge is computed in this setting and finally projected onto the original market. We notice that the vega multipliers are the same for the two hedging schemes. Moreover, when the driving noise is Gaussian distributed, the two local risk minimization problems lead to the same solution as the extended Girsanov principle and the minimal martingale measure are associated with the same GARCH diffusion dynamics. More generally, this result also holds true in the presence of arbitrary symmetric GARCH innovations. The use of the partial derivative of the option price with respect to the asset price, \( \Delta_{t,S} \), as the appropriate hedging ratio within the class of GARCH diffusion models is justified only when either \( M_3 = 2\omega_3 \) or, in particular, when both quantities are zero. The latter corresponds to the case of a GARCH underlying model without a leverage effect driven by symmetric innovations. In general, if we fit an asymmetric GARCH model to historical data, we obtain a negative leverage effect (i.e. \( \omega_3 > 0 \)) and a negative skewness (\( M_3 < 0 \)). Hence, a non-negative value of the option vega leads to a smaller value of the adjusted hedge ratio in (3.25) or (3.26).

Examining the expressions of the local risk minimizing strategies based on discrete time GARCH approximations and their diffusion limits, one can establish a relationship between them\(^{10}\). For example, if standard regularity assumptions hold, which ensure the convergence of the partial derivatives of option prices from GARCH to diffusions, we only need to show such a result for the corresponding vega multipliers. This is illustrated in the result below.

**Proposition 3.4** Suppose that \( (S_{kh,n}, \sigma^2_{(k+1)h,n}) \) follows the dynamics of (3.14)-(3.15) under the historical measure \( P_n \) and (3.19)-(3.20) under the risk neutral measure \( Q^{egp}_n \). Then, under the parametric constraints (3.16), the following limiting results for the vega multipliers defined in (3.2) and (3.4) hold:

\[
\lim_{h \to 0} V M^{P_n}_{(k+1)h,n} (S, \sigma^2) = \lim_{h \to 0} V M^{Q^{egp}_n}_{(k+1)h,n} (S, \sigma^2) = \frac{\sigma}{\sqrt{\omega_2}} (M_3 - 2\omega_3).
\]

Here, the vega multipliers are computed conditioned on the filtration \( F^S_{kh,n} = F_{kh,n} \cup \left\{ (S_{kh,n}, \sigma^2_{(k+1)h,n}) = (S, \sigma^2) \right\} \).

\(^{10}\)Prigent and Scaillet (2002) investigate the weak convergence of local risk minimization strategies to the standard delta hedges given by the partial derivatives of the option price with respect to the underlying. In particular, they show such a convergence result when the asset price is modeled using a stochastic volatility diffusion driven by uncorrelated Brownian motions. A key ingredient in their derivation is provided by the Markovian structure of the model, which is only the case in a GARCH(1,1) setup. However, a rigorous proof for such a result is beyond the aim of this paper.
4 Empirical analysis

In this section we assess the empirical performance of the different hedging methods which we theoretically studied above and we compare them with the ones obtained by more standard approaches, such as the ad hoc Black-Scholes strategy that is well known for its good performance and ease of implementation (see e.g. Dumas et al. (1998) and references therein). Additionally, we study the impact of the initial conditional variance estimation technique chosen at the time of computing the hedges, as well as the sensitivity of our results with respect to the choice of martingale measure.

4.1 Dataset description and modeling of the underlying asset

We use European call options on the S&P 500 index in order to conduct our study. They are known for their liquidity and high volume of trades. The option price quotes are recorded every Wednesday from Jan 7th, 2004 to Dec 29th, 2004. If a given Wednesday is a holiday, then we consider the next trading day. For a given date, we define the average of the bid-ask quotes as the observed option price and the closing price as the underlying asset price. The dataset contains a total of 1145 European call options contracts which have been obtained after applying similar selection techniques as those proposed by Dumas et al. (1998). We exclude contracts with times to maturity smaller than 7 and higher than 200 days, as well as moneyness outside the interval [0.9, 1.1]. We also set restrictions for the daily volume and daily open interest on our option data in order to eliminate inactive options; more specifically, only options with daily trading volume more than 200 in addition to at least 500 open interest are considered.

We model the log-returns of the S&P 500 index using the NGARCH(1,1) model under \( P \) from (3.5)-(3.6). All parameters are estimated via maximum likelihood (MLE) using the historical log-returns of the index during the in-sample period 1992–2003, for which we assume a constant daily interest rate \( r = 2.8 \cdot 10^{-5} \). Model estimation is carried out only once and the same model parameters are used in the hedging of all the options in the dataset. We shall consider two different distributions \( D(0,1) \) for the innovations \( \{\epsilon_t\} \) of our model. Firstly, we shall work with the standard Gaussian case, that is, \( D(0,1) = \mathcal{N}(0,1) \), and then we use special non-Gaussian GARCH models based on Normal Inverse Gaussian (NIG) innovations. The MLE parameters of the Gaussian version of (3.5)-(3.6) are:

\[
\alpha_0 = 9.941 \cdot 10^{-7}, \quad \alpha_1 = 0.041, \quad \beta_1 = 0.917, \quad \gamma = 0.863, \quad \text{and} \quad \lambda = 0.041.
\]

Concerning NIG innovations, we recall that this distribution has been well-studied in the context of the modeling financial returns by Barndorff-Nielsen (1997). More recently, the performance of GARCH option pricing models based on NIG innovations was investigated by Badescu et al. (2011) for European style options, and by Stentoft (2008) for American options, among others. Empirical findings indicate that the NIG density is more appropriate for capturing the negative skewness and thicker tails often displayed by asset returns than its Gaussian counterpart; moreover, option prices based on a NIG-GARCH model generally outperform the Gaussian benchmark. We recall that the NIG distribution, \( \text{NIG}(k,a,s,\ell) \), with parameters \( k, a, s \) and \( \ell \) has probability density
function given by:
\[
 f^P(x) = \frac{k}{\pi s} \exp \left[\sqrt{k^2 - a^2} + a \left(\frac{x - \ell}{s}\right)\right] K_1 \left(k \sqrt{1 + \left(\frac{x - \ell}{s}\right)^2}\right),
\]
where \(K_1(\cdot)\) represents the modified Bessel function of third kind and index 1. The parameter \(k\) measures the kurtosis of the distribution, \(a\) the asymmetry, \(s\) is the scale parameter, and \(\ell\) is the location of the distribution. The cumulant generating function is given by:
\[
 \kappa^P(z) = z\ell + \left(\sqrt{k^2 - a^2} - \sqrt{k^2 - (a + zs)^2}\right).
\]
(4.2)

Thus, the first two conditional historical cumulants are:
\[
 E^P[\epsilon_t \mid \mathcal{F}_t-1] = \frac{d\kappa^P_t(z)}{dz} \bigg|_{z=0} = \ell + \frac{as}{\sqrt{k^2 - a^2}},
\]
\[
 \text{Var}^P[\epsilon_t \mid \mathcal{F}_t-1] = \frac{d^2\kappa^P_t(z)}{dz^2} \bigg|_{z=0} = \frac{s^2k^2}{(\sqrt{k^2 - a^2})^3}.
\]

Since the GARCH innovations have mean zero and unit variance we can express the scale and location parameters as functions of \(a\) and \(k\). This leads to a reduction in the number of NIG parameters which need to be estimated.

The MLE parameters of the NIG version of the GARCH model from (3.5)-(3.6) are:

\[
 \alpha_0 = 8.665 \cdot 10^{-7}, \quad \alpha_1 = 0.047, \quad \beta_1 = 0.909, \quad \gamma = 0.860, \quad \text{and} \quad \lambda = 0.041.
\]

The estimated values for the NIG invariant parameters are \(k = 1.322\) and \(a = -0.144\), which produces innovations with skewness -0.250 and kurtosis 4.839.

### 4.2 Hedging methods and error estimation

The performance assessment that we carry out in this section consists of constructing, for each of the options in the dataset, a collection of replicating self-financing portfolios made out of a riskless asset and the underlying. These portfolios are constructed based on the hedges proposed in the paper and are rebalanced weekly or, more specifically, each of the days during the life of the contract in which option prices are available. The performance measure that we shall use for a given hedging strategy is the normalized hedging error that we define as follows: consider an option whose life starts at time \(t = 0\) and that expires at \(t = T\). Additionally, suppose that we know its price \(V_0\) at time \(t = 0\) and that this contract is hedged at times \(\{t_0 = 0, t_1, \ldots, t_K\}\); let \(\xi := \{\xi_{t_1}, \xi_{t_2}, \ldots, \xi_{t_{K+1}}\}\) and let \(\{S_{t_0}, S_{t_1}, \ldots, S_{t_K}\}\) be the corresponding hedges and prices of the underlying, respectively. The normalized hedging error NHE of this contract is defined as:

\[
 \text{NHE}(\xi) := \frac{|H(S_T) - V_0 - \sum_{i=0}^{K} \xi_{t_{i+1}} \cdot (S_{t_{i+1}} - S_{t_i})|}{V_0}
\]
that is, the NHE(\(\xi\)) of a contract with respect of a specific hedging prescription \(\xi\) is the absolute value of the difference between the value of the dynamically constructed self financing hedging portfolio and the terminal payoff of the option under consideration, written as a fraction of its price.

This hedging error measure is a price normalized version of the absolute hedging error used in Bakshi et al. (1997). The objective of this modification is to be able to compare hedging errors between options that do not have exactly the same strike and time to maturity. A similar measure was used by Poulsen et al. (2009). The hedging performances will be reported by computing the average NHEs associated with contracts whose specifications are not identical, but whose times to maturity and moneyness belong to a given pair of intervals.

The competing hedging strategies that we test are:

- \(\xi = (\xi_t)_{t \in \{1,2,\ldots,K+1\}}\), where \(\xi_t\) is the \(Q\)-local risk minimization (LRM) hedge computed using equation (2.15); we call these strategies “LRM”.

- \(\Delta_S = (\Delta_{t_i}S)_{i \in \{1,2,\ldots,K+1\}}\), where \(\Delta_{t_i}S\) is the instantaneous \(Q\)-delta hedge proposed by Duan (1995) and computed using equation (3.11); we call these approximation strategies “Delta”.

- \(\Delta^{SV} = (\Delta^{SV}_{t_i})_{i \in \{1,2,\ldots,K+1\}}\), where \(\Delta^{SV}_{t_i} := \Delta_{t_i}S + VM_i \cdot \Delta_{t_i}\sigma^2\) is the minimum variance instantaneous delta hedge computed using based on Proposition 3.2 and obtained as a vega correction of the previous hedge; we call these approximation strategies “Delta-SV”.

The results obtained with these hedges will be compared with a benchmark provided by the ad hoc Black-Scholes method implemented using the option prices in the dataset. We recall that this strategy consists of using the quoted option prices, associated with a cross section of contracts for any given date, to construct a volatility surface parametrized by strike and time to maturity; this is achieved by regressing the strikes and times to maturity of the available contracts on the standard Black-Scholes volatilities implied by their prices. As a result of this procedure, on each day for which option prices are available we obtain a function which assigns a volatility to each strike and time to maturity. The Black-Scholes delta obtained for a given option out of that volatility value is the so-called ad hoc delta which yields the hedging benchmark that we shall be using. We emphasize that the weekly hedging frequency that we shall enforce for all the methods considered in our study is dictated by the fact that the ad hoc Black-Scholes benchmark requires option prices in order to be implemented and these are only available weekly.

The ad hoc approach motivates two different ways to compute the hedges \(\xi, \Delta_S\), and \(\Delta^{SV}\). Indeed, the expressions which determine all these quantities involve expectations under the risk neutral measure \(Q\) which will be computed using Monte Carlo simulations by producing price paths via the GARCH model specification that we are using. The path simulation is initialized by providing the initial price \(S_0\), as well as initial values of the innovation \(\epsilon_0\) and volatility \(\sigma_0\). Once the initial volatility \(\sigma_0\) has been chosen, the initial innovation \(\epsilon_0\) is fully determined by the GARCH formula using the the log-return \(y_0\) of the underlying. Hence the only term that remains to be specified is \(\sigma_0\). We explore two possibilities for that. Firstly, we consider Monte Carlo estimation using paths initialized with the GARCH volatility. This strategy consists of initializing the path using the conditional volatility at time \(t = 0\) associated with the model under consideration and the historical sample of log-returns of the underlying asset. The
implementation of this choice requires knowledge of only the historical prices. Additionally, paths are initialized in the same way regardless of the specification of the contract that we wish to hedge. Secondly, we propose a Monte Carlo estimation using paths initialized with the ad hoc volatility. This approach relies on initializing the price paths with volatilities adapted to the strike and time to maturity of the option that we want to handle by using the ad hoc Black-Scholes volatility obtained from the regression we explained above using the option prices quoted on the day in which the hedge is constructed. We emphasize that the second method uses more market information and, hence, the comparison of ad hoc methods with their GARCH volatility based counterparts is not completely fair.

As already mentioned, the hedges $\xi, \Delta_S$, and $\Delta^{SV}$ will be computed using a risk neutral measure $Q$. Given that the GARCH model chosen for the underlying makes the associated market incomplete, the choice of martingale measure $Q$ is an issue and hence it is advisable to study the sensitivity of our results with respect to this measure. We do so by considering an exponential affine stochastic discount factor, also known as an Esscher transform, in addition to the extended Girsanov principle proposed in the previous section. For completeness, we provide below the Radon-Nikodym derivatives of the GARCH models based on $\text{NIG}(k, a, s, \ell)$ innovations associated with both martingale measures.

The extended Girsanov principle density process is given by:

$$\frac{dQ_{\text{egp}}}{dP} = \exp \left[ \frac{a\lambda T}{s} \prod_{t=1}^{T} \frac{K_1 \left( k \sqrt{1 + \left( \frac{a + \lambda - \ell}{s} \right)^2} \right)}{K_1 \left( k \sqrt{1 + \left( \frac{a - \ell}{s} \right)^2} \right)} \right]. \quad (4.3)$$

For the conditional Esscher transform, denoted by $Q^{\text{ess}}$, the Radon-Nikodym derivative is:

$$\frac{dQ^{\text{ess}}}{dP} = \exp \left[ -T \sqrt{k^2 - a^2} \prod_{t=1}^{T} \exp \left[ \hat{\theta}_t \sigma_t (\epsilon_t - \ell) + \sqrt{k^2 - (a + \hat{\theta}_t \sigma_t s)^2} \right] \right]. \quad (4.4)$$

Here, for any $t \in [0, \cdots, T]$, the Esscher parameter $\hat{\theta}_t$ is the unique solution of the so called martingale equation that, in the NIG distribution case, is given by the closed form expression:

$$\hat{\theta}_t = -\frac{1}{2} - \frac{a}{\sigma_t s} - \frac{1}{2} \sqrt{\left( \frac{\kappa_T^T (\sigma_t) - (\lambda + \ell)\sigma_t^2}{\sigma_t^2 s^2} \right)^2 - \frac{4k^2}{\sigma_t^2 s^2 + (\kappa_T^T (\sigma_t) - (\lambda + \ell)\sigma_t^2)^2}} - 1. \quad (4.5)$$

This identity ensures that the discounted asset prices are martingales under $Q^{\text{ess}}$. Since the hedges that we are interested in require the computation of expectations under a martingale measure $Q$, an important technical point is that the Monte Carlo estimator will be implemented using variance reduction techniques adapted to the martingale character of the discounted prices. Indeed, when $Q$ is given by the extended Girsanov principle, we shall directly simulate under $Q$ using the corresponding expressions (2.4)–(2.5) and shall correct the resulting paths using the empirical martingale simulation (EMS) technique proposed by Duan and Simonato (1998). When $Q$ is the Esscher measure, it is preferable to simulate under the physical measure and to correct the result using the corresponding Radon-Nikodym derivative (4.4) at the time of computing the expectation.
4.3 Numerical results

This subsection presents the numerical results obtained in our empirical study. A first set of computations is contained in Tables 1 and 2. Table 1 (respectively Table 2) contains the average normalized hedging errors associated with different hedges computed using Gaussian, (respectively NIG), GARCH Monte Carlo simulation. Each entry in the table has been computed by averaging the normalized hedging errors committed when handling the options contained in the corresponding moneyness-time to maturity bin. The results in both tables are associated to hedges computed using the extended Girsanov principle martingale measure and Monte Carlo simulations with paths that have been initialized with the GARCH implied instantaneous conditional volatility as well as the ad hoc volatility. Additionally, results associated with the ad hoc Black-Scholes benchmark are also reported.

A first examination of the tables indicates that the local risk minimization methods outperform the ad hoc Black-Scholes benchmark for both methods and distributions considered. Regarding delta hedging, this is the case only for the ad hoc versions. In general, the hedging schemes computed based on the ad hoc implied volatility starting values consistently outperform the results obtained using Monte Carlo paths initialized using the GARCH conditional volatility. In the case of the delta hedges, the improvement is only limited for $\Delta_S$: e.g. the overall average NHE goes from 0.586 to 0.549 for the Gaussian innovations, and from 0.569 to 0.534 for the NIG. The improvement is outstanding for $\Delta^{SV}$: e.g. the overall average NHE goes from 0.572 to 0.204 for Gaussian innovations, and 0.553 to 0.183 for the NIG. This is mainly due to the dependence on initial volatility for the vega correction in this hedge. This effect is more pronounced for longer maturity options. For example, in the case of NIG innovations, for maturities between 7 and 71 days, the average NHE varies from 0.627 to 0.495, while for maturities greater than 135 days it varies from 0.674 to 0.026. The same effect can be observed by analyzing the results for each moneyness bin, where the improvement is more pronounced for in-the-money options. This can be further visualized in Figure 1 where we recall that, in contrast to the results presented in Tables 1 and 2, the average errors reported in the figures have been computed by dividing the moneyness interval $[0.9, 1.1]$ into ten bins, instead of five for the tables. The vega correction that differentiates the proposed stochastic volatility adjusted delta $\Delta^{SV}$ and the standard option delta $\Delta_S$ has a positive effect in the empirical hedging performance. For example, in the NIG-GARCH case, the total average NHE goes from 0.569 to 0.553 when the historical GARCH implied variance is used as a starting value.

We then analyze the importance of using different conditional distributions for the GARCH model. The results in Tables 1 and 2 indicate that hedges carried out using Gaussian GARCH models systematically exhibit a lower performance than their NIG counterparts, regardless of the method considered and the contract specifications. This fact is further graphically illustrated in Figure 2, where we notice that the differences between the two models are more pronounced for out-of-money options. Thus, the use of a more appropriate skewed and leptokurtic distribution also improves the overall hedging performance.

The sensitivity of the hedging performance in the NIG-GARCH case with respect to the choice of pricing measure is very limited. In Table 3 we have recomputed the local risk minimization $\xi$ and delta $\Delta_S$ hedges using the Esscher transform instead of the extended Girsanov principle which had been used in Tables 1 and 2. As can be
seen, the total average NHE goes from 0.496 for the extended Girsanov principle to 0.492 for the Esscher transform in the case of local risk minimization, and from 0.569 to 0.572 for the delta hedges. This analysis is not carried out for the Gaussian case since both martingale measures provide the same risk-neutralized dynamics.

<table>
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<th>Method</th>
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<th></th>
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<td>0.025</td>
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<td>0.002</td>
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Table 1: Average normalized hedging errors associated with the different hedges computed using Gaussian GARCH Monte Carlo simulation. BS stands for Black-Scholes and LRM for local risk minimization. Delta indicates the hedging scheme associated with the ratio $\Delta_S$ and Delta-SV that of the vega corrected delta $\Delta^{SV}$. When the name of the method contains “ad hoc”, it means that the Monte Carlo simulations have been initialized using the ad hoc volatility; otherwise, the initialization is carried out using the instantaneous GARCH conditional volatility. Each entry in the table has been computed by averaging the normalized hedging errors committed when handling the options contained in the corresponding moneyness-time to maturity bin.
<table>
<thead>
<tr>
<th>Method</th>
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<td>1.545</td>
<td>1.239</td>
<td>0.364</td>
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<td>0.025</td>
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<td>0.944</td>
<td>0.576</td>
<td>0.452</td>
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<td>0.742</td>
<td>0.428</td>
<td>0.267</td>
<td>—</td>
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<td>1.189</td>
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Table 2: Average normalized hedging errors associated with the different hedges computed using NIG-GARCH Monte Carlo simulation. BS stands for Black-Scholes and LRM for local risk minimization. Delta indicates the hedging scheme associated to the ratio $\Delta_S$ and Delta-SV that of the vega corrected delta $\Delta^SV$. When the name of the method contains “ad hoc”, it means that the Monte Carlo simulations have been initialized using the ad hoc volatility; otherwise, the initialization is carried out using the instantaneous GARCH conditional volatility. Each entry in the table has been computed by averaging the normalized hedging errors committed when handling the options contained in the corresponding moneyness-time to maturity bin.
### COMPARISON BETWEEN ERRORS COMPUTED USING EGP AND ESSCHER KERNELS

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<tr>
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<td>135 ≤ T ≤ 199</td>
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<tr>
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<tr>
<td></td>
<td>71 ≤ T ≤ 135</td>
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<td>0.638</td>
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<tr>
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<tr>
<td>Average NHE</td>
<td></td>
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<td>0.879</td>
</tr>
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Table 3: Average normalized hedging errors associated with the local risk minimization \( \xi \) and delta \( \Delta_S \) hedges computed using NIG-GARCH Monte Carlo simulations with respect to the pricing measures provided by the extended Girsanov principle and the Esscher transformation. Each entry in the table has been computed by averaging the normalized hedging errors committed when handling the options contained in the corresponding moneyness-time to maturity bin.
Quadratic hedging schemes for non-Gaussian GARCH models

Figure 1: Comparison between the hedging performances obtained using the ad hoc Black-Scholes method with the local risk minimizing ratios $\xi$ and the vega corrected hedges $\Delta^{SV}$ computed using NIG-GARCH models for the underlying asset initialized with both the instantaneous GARCH conditional volatility and the ad hoc volatility implied by option prices. In contrast with the results presented in Tables 1 and 2, the average errors reported in these figures have been computed by dividing the moneyness interval $[0.9, 1.1]$ into ten bins (instead of five for the tables).

(a) Mean normalized hedging error for short maturity contracts. The contracts considered in this figure have times to maturity ranging from 7 to 71 days.

(b) Mean normalized hedging error for medium maturity contracts. The contracts considered in this figure have times to maturity ranging from 71 to 135 days.

(c) Mean normalized hedging error for long maturity contracts. The contracts considered in this figure have times to maturity ranging from 135 to 199 days.
Quadratic hedging schemes for non-Gaussian GARCH models

(a) Mean normalized hedging error for short maturity contracts. The contracts considered in this figure have times to maturity ranging from 7 to 71 days.

(b) Mean normalized hedging error for medium maturity contracts. The contracts considered in this figure have times to maturity ranging from 71 to 135 days.

(c) Mean normalized hedging error for long maturity contracts. The contracts considered in this figure have times to maturity ranging from 135 to 199 days.

Figure 2: Comparison of the hedging performances obtained using the local risk minimizing ratios $\xi$ and the vega corrected hedges $\Delta^{SV}$ computed using NIG-GARCH and Gaussian GARCH models for the underlying asset. In contrast with the results presented in Tables 1 and 2, the average errors reported in these figures have been computed by dividing the moneyness interval $[0.9, 1.1]$ into ten bins (instead of five for the tables).
5 Conclusions

In this paper we investigate the hedging of European options when the underlying is modeled using an asymmetric non-Gaussian GARCH model. Since the well-known minimal martingale measure is typically a signed measure for such models, the construction of local risk minimization (LRM) schemes with respect to the historical measure is not possible. Therefore, we first introduce the notion of LRM with respect to a martingale measure for general GARCH frameworks. When the time between two consecutive hedging trades is small, local risk minimization can be approximated by minimum variance hedges which depend on the option’s delta and vega. Such approximations can be viewed as generalizations of Duan’s (1995) delta hedge formula by taking into account the dependence of tomorrow’s conditional variance on today’s asset price. Duan’s result is recovered in the case when asset returns and their conditional variances are uncorrelated. Other potential hedge ratio candidates, which can be obtained using total derivative formulas, are discussed. Using the extended Girsanov principle as our pricing measure, we derive semi-explicit solutions for these minimum variance hedges under a general non-Gaussian framework. Finally, we compute the local risk minimizing hedging strategies for the non-Gaussian GARCH diffusion limits and we show their relationship with the discrete-time versions.

An extensive empirical analysis based on S&P 500 options is provided to test the performance of the proposed hedging schemes. The GARCH models considered are based on Gaussian and Normal Inverse Gaussian innovations. The hedging ratios are computed using Monte Carlo simulation and our schemes are implemented with two different initial conditional variance values: an implied GARCH variance obtained from historical returns and an ad hoc Black-Scholes implied variance. Our results indicate that under both scenarios the local risk minimization hedging strategy based on weekly rebalancing outperforms the ad hoc Black-Scholes benchmark. Duan’s (1995) delta hedge has the worst performance among all methods considered. However, the minimum variance approximation, based on the ad hoc initial variance, is the best hedging scheme with a hedging error almost three times smaller than the Black-Scholes counterpart. Our results are, thus, consistent with some of the findings from the continuous time hedging literature, according to which local risk minimization provides the best hedge when the two driving Brownian motions of the corresponding stochastic volatility model are correlated.

Finally, we test the sensitivity of the hedging schemes with respect to the martingale measure used. Numerical experiments indicate there are no significant differences between the Extended Girsanov Principle and the exponential stochastic discount factor used as the alternative pricing kernel. We found that, for all methods considered, the Normal Inverse Gaussian GARCH model consistently outperforms the Gaussian one.
References


Quadratic hedging schemes for non-Gaussian GARCH models


6 Appendix

6.1 Proof of Proposition 3.1

We prove only the first relationship, the second follows in a similar way. When the time between the observations is small, we can use the following approximation for the change in the option price based on the minimal martingale measure:

\[
\Pi_t^{Q_{\text{min}}} - \Pi_t^{Q_{\text{min}}} \approx \frac{\partial \Pi_t^{Q_{\text{min}}}}{\partial \sigma_{t+1}} (S_{t+1} - S_t) + \frac{\partial \Pi_t^{Q_{\text{min}}}}{\partial \sigma_{t+1}^2} (\sigma_{t+2}^2 - \sigma_{t+1}^2).
\]

(6.1)

Substituting this into the value process expression from (2.7) we have:

\[
\xi_{t+1}^P = \frac{\text{Cov}^P (V_{t+1}, S_{t+1} - S_t \mid F_t)}{\text{Var}^P [S_{t+1} - S_t \mid F_t]} = \frac{\text{Cov}^P (V_{t+1}, S_{t+1} \mid F_t)}{\text{Var}^P [S_{t+1} \mid F_t]}
\]

\[
\approx \frac{\text{Cov}^P (\Pi_t^{Q_{\text{min}}} + \frac{\partial \Pi_t^{Q_{\text{min}}}}{\partial S_t} (S_{t+1} - S_t) + \frac{\partial \Pi_t^{Q_{\text{min}}}}{\partial \sigma_{t+1}^2} (\sigma_{t+2}^2 - \sigma_{t+1}^2), S_{t+1} \mid F_t)}{\text{Var}^P [S_{t+1} \mid F_t]}
\]

\[
= \Delta_{t,S}^{Q_{\text{min}}} + \Delta_{t, \sigma^2}^{Q_{\text{min}}} \frac{\text{Cov}^P (S_{t+1} - S_t, \sigma_{t+2}^2 - \sigma_{t+1}^2 \mid F_t)}{\text{Var}^P [S_{t+1} - S_t \mid F_t]} = \Delta_{t,S}^{Q_{\text{min}}} + VM_{t+1} \Delta_{t, \sigma^2}^{Q_{\text{min}}}. \quad \blacksquare
\]

6.2 Proof of Proposition 3.2

We compute separately each term in the local risk minimization hedging under $Q^{\text{egp}}$. Firstly, for any fixed $t$, we assume that certain regularity conditions, which allow the interchange between the derivative and the expectation, are satisfied. Using (3.9), we can write

\[
\Delta_{t,S}^{Q^{\text{egp}}} = \frac{\partial \Pi_t^{Q_{\text{egp}}}}{\partial S_t} = e^{-r(T-t)} \frac{\partial}{\partial S_t} E^Q [\max \{(S_T - K), 0\}] = e^{-r(T-t)} E^Q \left[ \frac{\partial S_T}{\partial S_t} 1_{\{S_T > K\}} \right]
\]

\[
= e^{-r(T-t)} E^Q \left[ e^{r(T-t)} \frac{1}{2} \sum_{i=t+1}^{T} \kappa_{i}^* (\sigma_i) + \sum_{i=t+1}^{T} \sigma_i^* e^*(\kappa_{t+i}) \mathbf{1}_{\{S_T > K\}} \right] = e^{-r(T-t)} E^Q \left[ \frac{S_T}{S_t} \mathbf{1}_{\{S_T > K\}} \right].
\]

Secondly, we compute the option vega $\Delta_{t, \sigma^2}^{Q^{\text{egp}}} = \frac{\partial \Pi_t^{Q_{\text{egp}}}}{\partial \sigma_{t+1}^2}$.

We start from (3.10) in order to rewrite (3.9) as

\[
S_T = S_t e^{r(T-t) - \kappa_{t+1}^*(\sigma_{t+1}) + \sigma_{t+1}^* e_{t+1}^*} \left( \sqrt{\alpha_0} A(t+l,t+1) + \sigma_{t+1}^* B(t+l,t+1) + \sum_{l=2}^{T-l} \sqrt{\alpha_0} A(t+l,t+1) + \sigma_{t+1}^* B(t+l,t+1) \right) e_{t+1}^*.
\]

Using this expression we compute the derivative:

\[
\frac{\partial S_T}{\partial \sigma_{t+1}^2} = \frac{S_T}{2} \sum_{l=1}^{T-l} \left( \frac{B(t+l,t+1)}{\sigma_{t+l}} \right) \left( e_{t+l}^* - \kappa_{t+l}^* (\sigma_{t+l}) \right),
\]
Thus, we obtain for the numerator:

\[
\Delta Q^{\text{ggp}}_{t,\sigma^2} = \frac{\partial \Pi^{\text{ggp}}}{\partial \sigma_{t+1}^2} = e^{-r(T-t)} \frac{\partial}{\partial \sigma_{t+1}^2} E_t^Q \left[ \max \{(S_T - K), 0\} \right] = e^{-r(T-t)} E_t^Q \left[ \frac{\partial S_T}{\partial \sigma_{t+1}^2} \mathbf{1}_{\{S_T > K\}} \right]
\]

\[
= \frac{e^{-r(T-t)}}{2} E_t^Q \left[ S_T \sum_{l=1}^{T-t} \frac{B(t+l,t+1)}{\sigma_{t+l}^2} \left( \epsilon_{t+l}^* - \kappa_{t_{t+l}} (\sigma_{t+l}) \right) \mathbf{1}_{\{S_T > K\}} \right].
\] (6.2)

In order to prove the relationship for the vega multiplier in (3.13), we rewrite equations (3.7) and (3.8) as:

\[
\frac{S_{t+1} - S_t}{\sigma_{t+2}^2 - \sigma_{t+1}^2} = \alpha_0 + \alpha_1 \sigma_{t+1}^2 (\epsilon_{t+1}^* - \gamma - \lambda)^2 + (\beta_1 - 1) \sigma_{t+1}^2.
\]

Using the fact that \(\kappa_{t_{t+1}} (\cdot) = \kappa_{t_{t+1}}^* (\cdot)\), the denominator becomes:

\[
\operatorname{Var}^{\text{ggp}}[S_{t+1} - S_t \mid \mathcal{F}_t] = S_t^2 e^{2(\kappa_{t_{t+1}} (\sigma_{t+1}) - 2 \kappa_{t_{t+1}} (\sigma_{t+1}) - 1)}.
\] (6.3)

The numerator is then:

\[
\operatorname{Cov}^{\text{ggp}}(S_{t+1} - S_t, \sigma_{t+2}^2 - \sigma_{t+1}^2 \mid \mathcal{F}_t) = \alpha_1 S_t e^{-\kappa_{t_{t+1}} (\sigma_{t+1})} \sigma_{t+1}^2 \operatorname{Cov}^{\text{ggp}}(\epsilon_{t_{t+1}}^*, \epsilon_{t_{t+1}}^* - \gamma - \lambda)^2 \mid \mathcal{F}_t) = \alpha_1 S_t e^{-\kappa_{t_{t+1}} (\sigma_{t+1})} \sigma_{t+1}^2 \operatorname{Cov}^{\text{ggp}}(\epsilon_{t_{t+1}}^*, \epsilon_{t_{t+1}}^* - 2(\gamma + \lambda) \epsilon_{t_{t+1}}^* \mid \mathcal{F}_t).
\]

Next we express the above in terms of the cumulant generating function of the innovations:

\[
\operatorname{Cov}^{\text{ggp}}(e^{\sigma_{t+1}^* \epsilon_{t_{t+1}}^*}, \epsilon_{t_{t+1}}^* \mid \mathcal{F}_t) = E^{\text{ggp}} (e^{\sigma_{t+1}^* \epsilon_{t_{t+1}}^*} \mid \mathcal{F}_t) = e^{\kappa_{t_{t+1}} (\sigma_{t+1})} \kappa_{t_{t+1}}^* (\sigma_{t+1}),
\]

\[
\operatorname{Cov}^{\text{ggp}}(e^{\sigma_{t+1}^* \epsilon_{t_{t+1}}^*}, \epsilon_{t_{t+1}}^* \mid \mathcal{F}_t) = E^{\text{ggp}} (e^{\sigma_{t+1}^* \epsilon_{t_{t+1}}^*} \mid \mathcal{F}_t) - E^{\text{ggp}} (e^{\sigma_{t+1}^* \epsilon_{t_{t+1}}^*} \mid \mathcal{F}_t) = e^{\kappa_{t_{t+1}} (\sigma_{t+1})} \left( (\kappa_{t_{t+1}}^* (\sigma_{t+1}))^2 + \kappa_{t_{t+1}}'' (\sigma_{t+1}) - 1 \right).
\]

Thus, we obtain for the numerator:

\[
\operatorname{Cov}^{\text{ggp}}(S_{t+1} - S_t, \sigma_{t+2}^2 - \sigma_{t+1}^2 \mid \mathcal{F}_t) = \alpha_1 e^\gamma S_t \sigma_{t+1}^2 \left( (\kappa_{t_{t+1}}^* (\sigma_{t+1}))^2 + (\gamma + \lambda) \kappa_{t_{t+1}}' (\sigma_{t+1}) + \kappa_{t_{t+1}}'' (\sigma_{t+1}) - 1 \right).
\] (6.4)

Substituting (6.3) and (6.4) into (3.13), we obtain the desired result for the vega multiplier under \(Q^{\text{ggp}}\).

6.3 Proof of Proposition 3.4

We derive only the limit for the vega multiplier under \(Q^{\text{ggp}}_n\). The equation under the physical measure follows in a similar way. For notational convenience we omit the subscripts for the conditional cumulant generating function of \(\epsilon_{(k+1)h,n}\), and we further assume that all limits are computed conditioned on the enlarged filtration \(\mathcal{F}_{kh,n}\).
Using a similar proof as in the previous proposition, and \( \alpha_1^2(h) = \omega_2 h + o(h) \), the vega multiplier limit reduces to:

\[
\lim_{h \to 0} VM_{(k+1)h,n}^{Q_{(k+1)h,n}^{1\sigma}} (S, \sigma^2) = \lim_{h \to 0} \frac{\text{Cov}_{(k+1)h,n}^{Q_{(k+1)h,n}^{1\sigma}} \left( S_{(k+1)h,n} - S_{kh,n}, \sigma^2_{(k+1)h,n} - \sigma^2_{kh,n}, F_{kh,n}^{(S, \sigma^2)} \right)}{\text{Var}_{(k+1)h,n}^{Q_{(k+1)h,n}^{1\sigma}} \left( S_{(k+1)h,n} - S_{kh,n} \mid F_{kh,n}^{(S, \sigma^2)} \right)} = \sqrt{\omega_2} \frac{\sigma^2}{S} \lim_{h \to 0} \frac{Q_{(k+1)h,n}}{R_{(k+1)h,n}^{(S, \sigma^2)}}.
\]

Here, \( Q_{(k+1)h,n} \) and \( R_{(k+1)h,n} \) are functions of \( h \) conditionally on \( F_{kh,n}^{(S, \sigma^2)} \), which are then given by:

\[
Q_{(k+1)h,n} = \sqrt{h} \left( \kappa' \left( \sqrt{h} \sigma_{(k+1)h,n} \right) \right)^2 - 2 \left( \sqrt{h} \gamma(h) + h \rho_{(k+1)h,n} \right) \kappa' \left( \sqrt{h} \sigma_{(k+1)h,n} \right) + \sqrt{h} \left( \kappa'' \left( \sqrt{h} \sigma_{(k+1)h,n} \right) - 1 \right)
\]

\[
R_{(k+1)h,n} = e^{\kappa \left( 2 \sqrt{h} \sigma_{(k+1)h,n} \right) - 2 \kappa \left( \sqrt{h} \sigma_{(k+1)h,n} \right) - 1}.
\]

We first illustrate some useful limits which are needed for computing the above limit ratio. These are based on second order Taylor expansions around the origin for the cumulant generating functions and its first two derivatives evaluated at \( u = \sqrt{h} \sigma_{(k+1)h,n} \):

\[
\kappa \left( \sqrt{h} \sigma_{(k+1)h,n} \right) = \kappa(0) + \sqrt{h} \sigma_{(k+1)h,n} \kappa'(0) + \frac{h \sigma_{(k+1)h,n}^2}{2} \kappa''(0) + o(h),
\]

\[
\kappa' \left( \sqrt{h} \sigma_{(k+1)h,n} \right) = \kappa'(0) + \sqrt{h} \sigma_{(k+1)h,n} \kappa''(0) + \frac{h \sigma_{(k+1)h,n}^2}{2} \kappa^{(3)}(0) + o(h),
\]

\[
\kappa'' \left( \sqrt{h} \sigma_{(k+1)h,n} \right) = \kappa''(0) + \sqrt{h} \sigma_{(k+1)h,n} \kappa^{(3)}(0) + \frac{h \sigma_{(k+1)h,n}^2}{2} \kappa^{(4)}(0) + o(h).
\]

Using the relationships between the cumulants and the moments of \( \epsilon_{(k+1)h,n} \) we derive the following limits:

\[
\lim_{h \to 0} \frac{\kappa \left( \sqrt{h} \sigma_{(k+1)h,n} \right)}{h} = \frac{1}{2} \sigma^2,
\]

\[
\lim_{h \to 0} \frac{\kappa' \left( \sqrt{h} \sigma_{(k+1)h,n} \right)}{\sqrt{h}} = \sigma,
\]

\[
\lim_{h \to 0} \frac{\kappa'' \left( \sqrt{h} \sigma_{(k+1)h,n} \right)}{\sqrt{h}} - 1 = M_3 \sigma.
\]

Here, \( \rho_{(k+1)h,n} \) denotes the derivative of the market price of risk with respect to \( h \). We now apply l'Hôpital's rule for calculating the limit. After some tedious algebraic manipulations, the limits of the derivatives of the three quantities in \( Q_{(k+1)h,n} \) are given by:

\[
\lim_{h \to 0} Q_{1,(k+1)h,n} = 0, \quad \lim_{h \to 0} Q_{2,(k+1)h,n} = \omega_3 \sigma, \quad \lim_{h \to 0} Q_{3,(k+1)h,n} = M_3 \sigma.
\]  

(6.5)

Similarly, we obtain \( \lim_{h \to 0} R_{(k+1)h,n}^{(S, \sigma^2)} = \sigma^2 \). Substituting this result and (6.5) into the vega multiplier limit we have:

\[
\lim_{h \to 0} VM_{(k+1)h,n}^{Q_{(k+1)h,n}^{1\sigma}} (S, \sigma^2) = \sqrt{\omega_2} \frac{\sigma^2}{S} \lim_{h \to 0} \frac{Q_{(k+1)h,n}}{R_{(k+1)h,n}^{(S, \sigma^2)}} = \sqrt{\omega_2} \frac{\sigma^2}{S} \lim_{h \to 0} \frac{Q_{(k+1)h,n}}{R_{(k+1)h,n}^{(S, \sigma^2)}} = \frac{\sigma}{\sqrt{\omega_2}} (M_3 - 2 \omega_3). \]
